



262B-Lecture 20

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- Foc (geometric) : If x_* is a Local min, then

$$\nabla f(x_*)^T \Delta x \geq 0 \quad \forall \Delta x \in T(x_*) \rightarrow \text{Tangent Cone}$$

(no descent direction in the tangent cone).

- Also, KKT Conditions (need constraint qualification)
(Foc algebraic) :

$$\left\{ \begin{array}{l} 1 - \nabla f(x_*) + \sum_{i=1}^m \lambda_i^* \nabla h_i(x_*) + \sum_{j=1}^r \mu_j^* \nabla g_j(x_*) = 0 \\ 2 - \mu \geq 0 \\ 3 - \mu_j^* = 0 \quad \text{if } j \notin A(x_*) \end{array} \right.$$

Due to Farkas Lemma, $\exists (\lambda_*, \mu_*)$ satisfying 1, 2, 3

if and only if

all linear in (λ, μ)

$$\nabla f(x_*)^T \Delta x \geq 0 \quad \forall \Delta x \in V(x_*)$$

where :

$$V(x_*) = \left\{ \Delta x \mid \begin{array}{l} \nabla h_i(x_*)^T \Delta x = 0 \quad i = 1, \dots, m \\ \nabla g_j(x_*)^T \Delta x \leq 0 \quad j \in A(x_*) \end{array} \right.$$

Cone of first-order directions

Thm: Consider a local min x_* . It satisfies

KKT $(\exists \lambda_*, \mu_*$ satisfying 1, 2, 3) if and only if

$$\nabla f(x_*)^T \Delta x \geq 0 \quad \forall \Delta x \in V(x_*)$$

→ Constraint qualifications are to bridge the gap between $V(x_*)$ and $T(x_*)$.

Special case: $V(x_*) = T(x_*)$

Def: A point y is called quasi-regular

if $V(y) = T(y)$. This is the best constraint qualification, but maybe hard to check (regularity is easy to check).

Thm: $T(y) \subseteq V(y) \quad \forall y: \text{feasible}$

Proof: pick $\Delta x \in T(y)$ and then show

$$\Rightarrow \exists \underbrace{\{y^{(k)}\}}_{\text{feasible}} \rightarrow y \quad \text{s.t.} \quad \frac{\Delta x}{\|\Delta x\|} = \lim_{k \rightarrow \infty} \frac{y^{(k)} - y}{\|y^{(k)} - y\|} \quad \Delta x \in V(y)$$

$$0 = h_i(y^{(k)}) = \underbrace{h_i(y)}_{=0} + \underbrace{(\nabla h_i(\tilde{y}^{(k)}))^T}_{\text{mean-value thm}} (y^{(k)} - y) \quad \text{①}$$

↳ feasibility

$j \in A(y)$:

$$0 \geq g_j(y^{(k)}) = \underbrace{g_j(y)}_{=0} + \underbrace{(\nabla g_j(\tilde{y}^{(k)}))^T}_{\text{(active constraint)}} (y^{(k)} - y) \quad \text{②}$$

↳ feasibility

①, ② as $k \rightarrow \infty$: $\nabla h_i(y)^T \Delta x = 0$

$\nabla g_j(y)^T \Delta x \leq 0$

$\Delta x \in V(y)$

Duality:

$$\text{Primal problem (P):} \quad \min f(x)$$
$$\text{s.t.} \quad h_i(x) = 0 \quad i=1, \dots, m$$
$$g_j(x) \leq 0 \quad j=1, \dots, r$$

and $x \in X$

Lagrangian:

$$L(x, \lambda, \mu) = f(x) + \sum_{i=1}^m \lambda_i h_i(x) + \sum_{j=1}^r \mu_j g_j(x)$$

Define: $f_* = \inf_{\substack{x \in X \\ h(x)=0 \\ g(x) \leq 0}} f(x)$

Thm: $\inf_{x \in X} L(x, \lambda, \mu) \leq f_* \quad \forall (\lambda, \mu) \text{ s.t. } \mu_j \geq 0$

proof: $\inf_{x \in X} L(x, \lambda, \mu) \leq \inf_{\substack{x \in X \\ h(x)=0 \\ g(x) \leq 0}} L(x, \lambda, \mu) \leq \inf_{\substack{x \in X \\ h(x)=0 \\ g(x) \leq 0}} f(x) = f_*$

smaller feasible set

(since $\lambda_i h_i(x) = 0, \mu_j g_j(x) \leq 0$ over the set)

Dual function: $q(\lambda, \mu) = \inf_{x \in X} \underbrace{l(x, \lambda, \mu)}$

So, $q(\lambda, \mu) \leq f_*$ $\forall (\lambda, \mu) : \mu \geq 0$

So, $q(\dots)$ provides a lower bound on the primal problem. If $q(\lambda, \mu) = -\infty$, then the lower bound is useless.

Domain of dual function:

$$D = \{(\lambda, \mu) \mid q(\lambda, \mu) > -\infty\}$$

Thm: Domain D of dual function = convex set
negative dual function over D = convex function

(no assumption of convexity for $f(x)$, $g(x)$, $h(x)$)

Proof: $\forall x, (\lambda, \mu), (\bar{\lambda}, \bar{\mu}), \alpha \in [0, 1]$

$$l(x, \alpha\lambda + (1-\alpha)\bar{\lambda}, \alpha\mu + (1-\alpha)\bar{\mu}) \stackrel{(\text{---})}{=} \alpha l(x, \lambda, \mu) + (1-\alpha) l(x, \bar{\lambda}, \bar{\mu})$$

Linearity of l
in second &
third arguments

$$\Rightarrow \inf_{x \in X} L(x, \alpha\lambda + (1-\alpha)\bar{\lambda}, \alpha\mu + (1-\alpha)\bar{\mu}) \geq$$

$$\alpha \inf_{x \in X} L(x, \lambda, \mu) + (1-\alpha) \inf_{x \in X} L(x, \bar{\lambda}, \bar{\mu})$$

$$\Rightarrow q(\alpha\lambda + (1-\alpha)\bar{\lambda}, \alpha\mu + (1-\alpha)\bar{\mu}) \geq \alpha q(\lambda, \mu) + (1-\alpha)q(\bar{\lambda}, \bar{\mu}) \quad (*)$$

If $q(\lambda, \mu) > -\infty$, $q(\bar{\lambda}, \bar{\mu}) > -\infty \Rightarrow (*)$

$$q(\alpha\lambda + (1-\alpha)\bar{\lambda}, \alpha\mu + (1-\alpha)\bar{\mu}) > -\infty$$

$\Rightarrow D$: convex set $\xrightarrow{(*)} q(\cdot, \cdot) = \text{concave on } D$.

Best Lower bound on f_* :

$$q_* = \sup_{\mu \geq 0} q(\lambda, \mu) \quad (\text{we can add } (\lambda, \mu) \in D)$$

Weak duality: $q_* \leq f_*$

primal
(P)

$$\begin{array}{ll} \min & f(x) \\ \text{s.t.} & h(x) = 0 \\ & g(x) \leq 0 \\ & x \in X \end{array}$$

non-convex



dual
(D)

$$\begin{array}{ll} \max & q(\lambda, \mu) \\ \text{s.t.} & \mu \geq 0 \end{array}$$

always convex
optimization after
 $\max q(\dots) \rightarrow$
 $\min -q(\dots)$

If $q_* = f_*$, it is said that strong duality holds or there is a zero duality gap.

Example: LP (Linear program)

$$\left\{ \begin{array}{ll} \min & a_0^T x + b_0 \\ \text{s.t.} & a_i^T x = b_i \quad i=1, \dots, m \quad \rightarrow \lambda_i \\ & c_j^T x \leq d_j \quad j=1, \dots, r \quad \rightarrow \mu_j \end{array} \right.$$

$$L(x, \lambda, \mu) = a_0^T x + b_0 + \sum_{i=1}^m \lambda_i (a_i^T x - b_i) + \sum_{j=1}^r \mu_j (c_j^T x - d_j)$$

$$\Rightarrow L(x, \lambda, \mu) = \underbrace{\left(a_0^T + \sum_{i=1}^m \lambda_i a_i^T + \sum_{j=1}^r \mu_j c_j^T \right)^T x}_{\textcircled{1}} + \underbrace{\left(b_0 + \sum_{i=1}^m (-\lambda_i b_i) + \sum_{j=1}^r (-\mu_j d_j) \right)}_{\textcircled{2}}$$

$$\inf_x L(x, \lambda, \mu) = -\infty \quad \text{if } \textcircled{1} \neq 0$$

$$\Rightarrow D = \left\{ (\lambda, \mu) \mid a_0^T + \sum_{i=1}^m \lambda_i a_i^T + \sum_{j=1}^r \mu_j c_j^T = 0 \right\}$$

$$\text{If } (\lambda, \mu) \in D \Rightarrow q(\lambda, \mu) = \textcircled{2}$$

\Rightarrow Dual optimization:

$$\max_{\lambda, \mu} b_0 - \sum_{i=1}^m \lambda_i b_i - \sum_{j=1}^r \mu_j d_j$$

$$\text{s.t. } \mu \geq 0$$

$$\left\{ a_0^T + \sum_{i=1}^m \lambda_i a_i^T + \sum_{j=1}^r \mu_j c_j^T = 0 \right\} \xrightarrow{\text{Domain!}}$$

LP

\Rightarrow Dual of LP = LP

QP (Quadratic program) :

$$\min \left(\frac{1}{2} x^T P_0 x \right) + a_0^T x + b_0$$

$$\text{s.t.} \quad a_i^T x = b_i \quad i=1, \dots, m \quad \longrightarrow \quad P_0 \succeq 0$$

$$c_j^T x \leq d_j \quad j=1, \dots, r \quad \text{to ensure convexity}$$

To simplify calculations, assume $P_0 \succ 0$.

$$\begin{aligned} \Rightarrow L(x, \lambda, \mu) &= \frac{1}{2} x^T P_0 x + \left(a_0^T + \sum_{i=1}^m \lambda_i a_i^T + \right. \\ &\left. \sum_{j=1}^r \mu_j c_j^T \right) x + \left(b_0 - \sum_{i=1}^m \lambda_i b_i - \sum_{j=1}^r \mu_j d_j \right) \quad (2) \\ &= \text{Convex in } x \quad (\text{shown it before :}) \end{aligned}$$

Lagrangian for convex opt is convex)

$$\min_x L(x, \lambda, \mu) \quad \longleftrightarrow \quad \nabla_x L(x, \lambda, \mu) = 0$$

(This is true if solution exists (not $-\infty$),

which is the case here since $P_0 \succ 0$)

$$\Rightarrow \underbrace{P_0 x}_{\text{Symmetric}} + \underbrace{\left(a_0^T + \sum_{i=1}^m \lambda_i a_i^T + \sum_{j=1}^r \mu_j c_j^T \right)^T}_{w(\lambda, \mu)} = 0$$

$$\Rightarrow q(\lambda, \mu) = \frac{1}{2} w(\lambda, \mu)^T P_0^{-1} P_0 P_0^{-1} w(\lambda, \mu)$$

$$- w(\lambda, \mu)^T P_0^{-1} w(\lambda, \mu) + \tilde{z}$$

\Rightarrow Dual optimization:

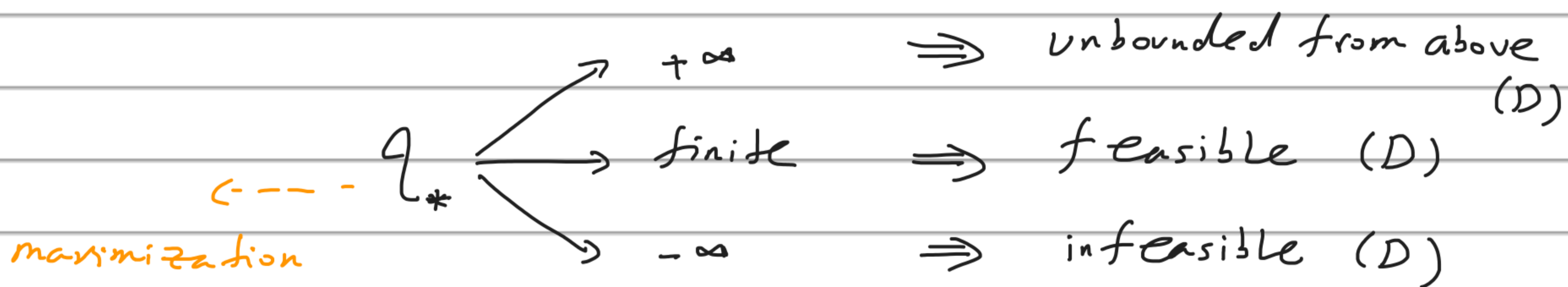
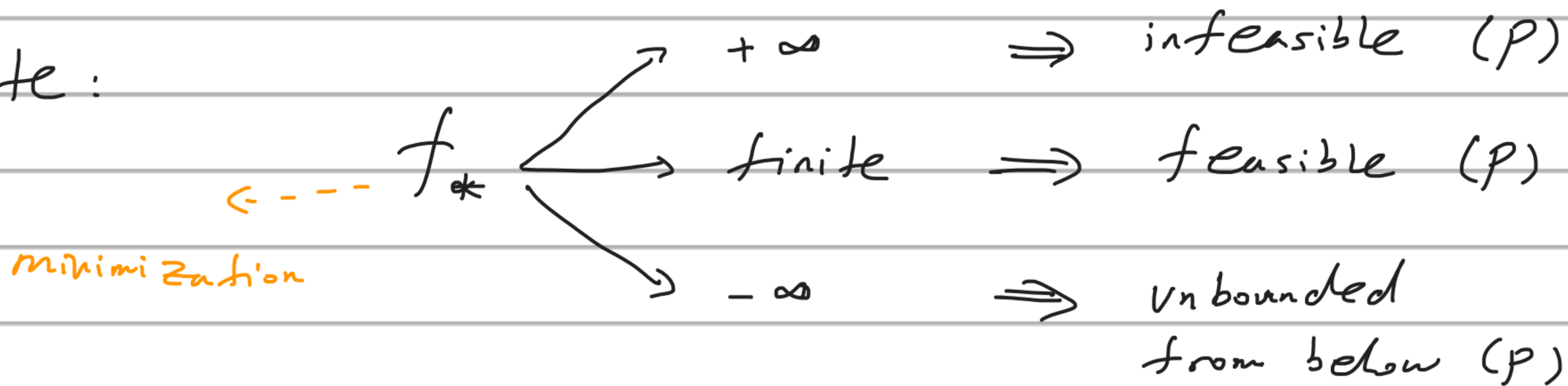
$$\begin{aligned} \max_{\lambda, \mu} & \left[-\frac{1}{2} \left(a_0^T + \sum_{i=1}^m \lambda_i a_i^T + \sum_{j=1}^r \mu_j c_j^T \right) P_0^{-1} \right. \\ & \left. \left(a_0 + \sum_{i=1}^m \lambda_i a_i + \sum_{j=1}^r \mu_j c_j \right) \right. \\ & \left. + \left(b_0 - \sum_{i=1}^m \lambda_i b_i - \sum_{j=1}^r \mu_j d_j \right) \right] \end{aligned}$$

Concave & quadratic in (λ, μ)

s.t. $\mu \geq 0$

$$\Rightarrow \text{Dual of QP} = \text{QP}$$

Note:



zero duality gap: $f_* = q_*$

it could happen that $f_* = q_* = -\infty$ or

$$f_* = q_* = +\infty$$

in these cases either (P) or (D) is infeasible

note that if (D) is unbounded from above,

then (P) is infeasible:

weak duality: $f_* \geq q_* = +\infty$

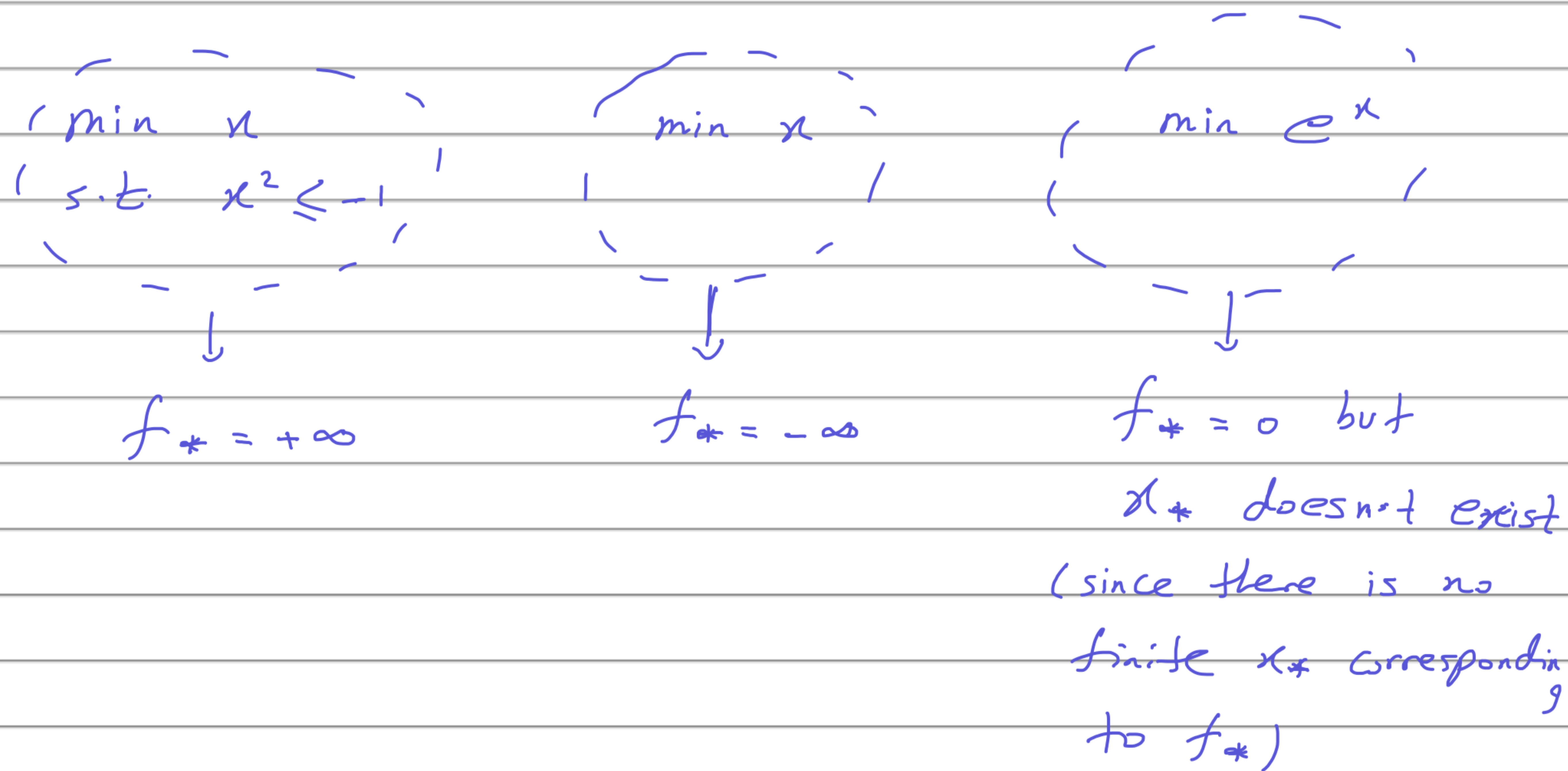
$$\Rightarrow f_* = +\infty$$

(generalization of Farkas Lemma for non-conver_{opt})

(P): Two questions:

1 - Is f_* finite?

2 - If so, does x_* exist?



To answer above questions & study duality gap,

we need the notion of geometric multipliers:

Def: (λ_*, μ_*) is called geometric multipliers

if $\mu_* \geq 0$ and $f_* = \inf_{x \in X} l(x, \lambda_*, \mu_*)$

Thm: - If there is no duality gap, then

set of geometric multipliers =

set of dual solutions

- If there is a duality gap ($f_* - q_* > 0$),

then

set of geometric multipliers = empty.

\Rightarrow existence of geometric multipliers



no duality gap

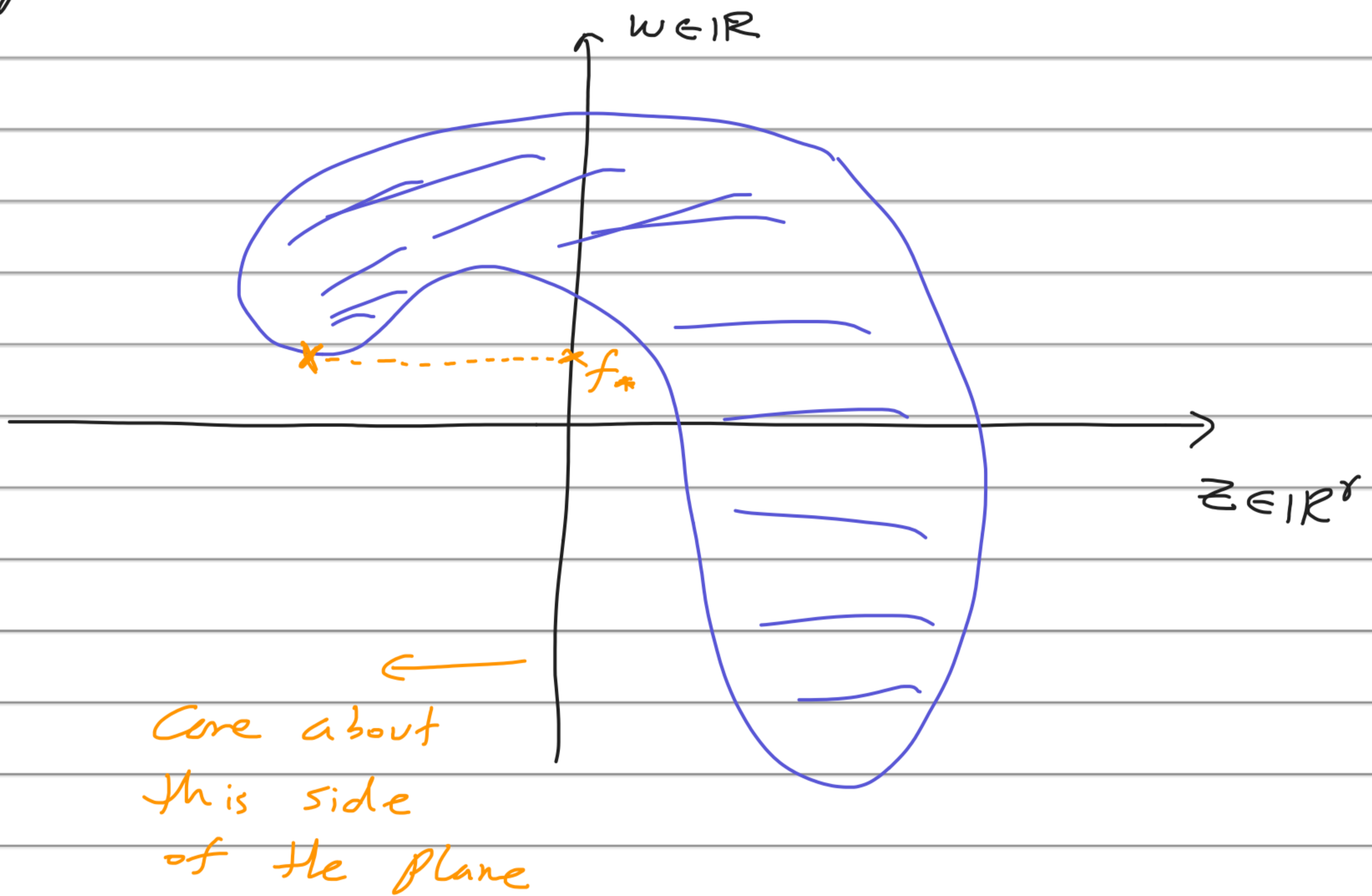
For simplicity, assume there is no equality constraint.

$\min f(x) \text{ s.t. } g(x) \leq 0, x \in X$

Define: $S = \{ (g(x), f(x)) \mid x \in X \}$

f_* : Find a point (z, w) in the set Σ
 $z \in \mathbb{R}^r$

s.t. $z \leq 0$ and w is as small as possible.



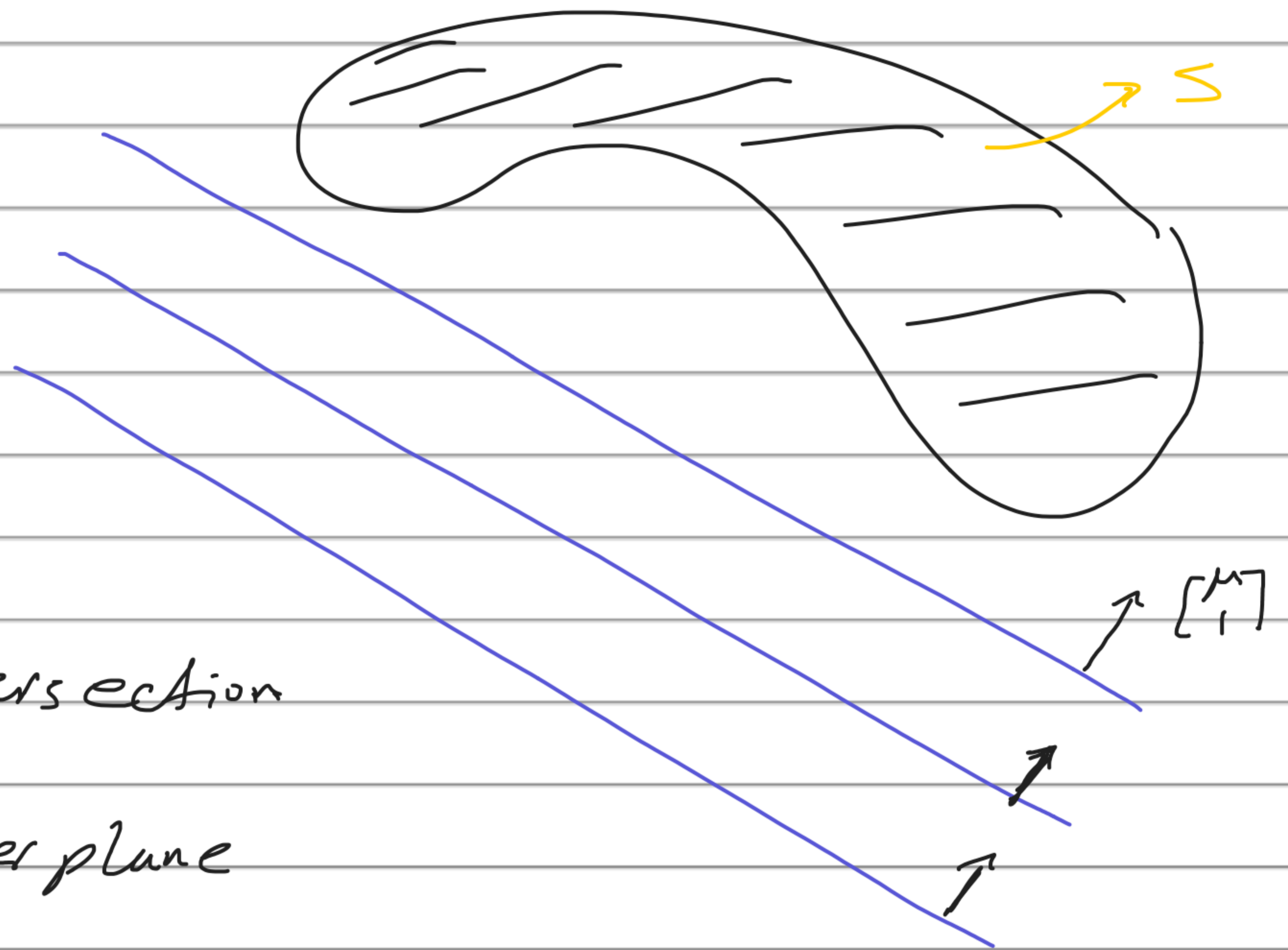
Also, $L(x, \mu) = f(x) + \mu^T g(x)$

$$= [\mu^T \quad 1] \begin{bmatrix} g(x) \\ f(x) \end{bmatrix}$$

$\begin{matrix} \xrightarrow{z} \\ \xrightarrow{w} \end{matrix}$

$$\Rightarrow \inf_{x \in X} L(x, \mu) = \inf_{(z, w) \in \Sigma} [\mu^T \quad 1] \begin{bmatrix} z \\ w \end{bmatrix}$$

- Consider all hyperplanes with the normal vector $\begin{bmatrix} \mu \\ 1 \end{bmatrix}$ that include S on their positive half space.



- Find the intersection of each hyperplane with the w -axis

- pick the hyperplane giving the highest level of interception with the w -axis.

- The value on the w -axis is $\inf_{x \in X} L(x, \mu)$

